

Wide Bandwidth PRECISION ANALOG MULTIPLIER

FEATURES

- WIDE BANDWIDTH: 10MHz typ
- ±0.5% MAX FOUR-QUADRANT ACCURACY
- INTERNAL WIDE-BANDWIDTH OP AMP
- EASY TO USE
- LOW COST

APPLICATIONS

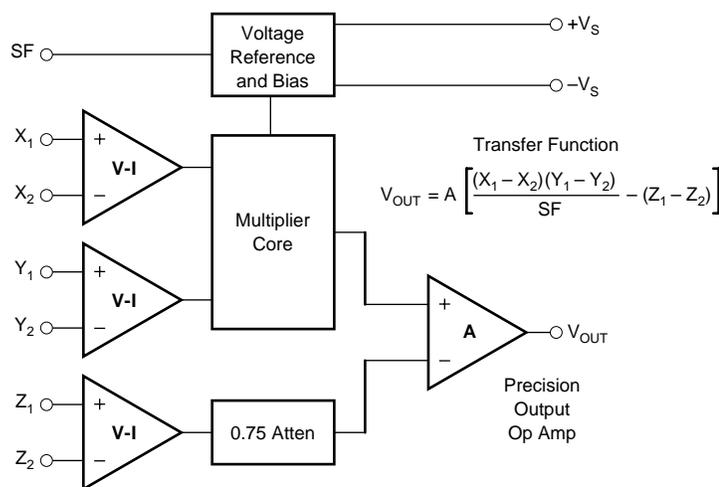
- PRECISION ANALOG SIGNAL PROCESSING
- MODULATION AND DEMODULATION
- VOLTAGE-CONTROLLED AMPLIFIERS
- VIDEO SIGNAL PROCESSING
- VOLTAGE-CONTROLLED FILTERS AND OSCILLATORS

DESCRIPTION

The MPY634 is a wide bandwidth, high accuracy, four-quadrant analog multiplier. Its accurately laser-trimmed multiplier characteristics make it easy to use in a wide variety of applications with a minimum of external parts, often eliminating all external trimming. Its differential X, Y, and Z inputs allow configuration as a multiplier, squarer, divider, square-rooter, and other functions while maintaining high accuracy.

The wide bandwidth of this new design allows signal processing at IF, RF, and video frequencies. The internal output amplifier of the MPY634 reduces design complexity compared to other high frequency multipliers and balanced modulator circuits. It is capable of performing frequency mixing, balanced modulation, and demodulation with excellent carrier rejection.

An accurate internal voltage reference provides precise setting of the scale factor. The differential Z input allows user-selected scale factors from 0.1 to 10 using external feedback resistors.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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SPECIFICATIONS

ELECTRICAL

At $T_A = +25^\circ\text{C}$ and $V_S = \pm 15\text{VDC}$, unless otherwise noted.

| MODEL | MPY634KP/KU | | | MPY634AM OBSOLETE | | | MPY634BM OBSOLETE | | | MPY634SM OBSOLETE | | | UNITS |
|--|---|-----|-----|---|-----|-----|-----------------------------|-----|-----|-----------------------------|-----|-----|--------------------------------|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| MULTIPLIER PERFORMANCE | $\frac{(X_1 - X_2)(Y_1 - Y_2)}{10V} + Z_2$ | | | $\frac{(X_1 - X_2)(Y_1 - Y_2)}{10V} + Z_2$ | | | | | | | | | |
| Transfer Function | | | | | | | * | | | * | | | |
| Total Error ⁽¹⁾ ($-10V \leq X, Y \leq +10V$) | ± 2.0 | | | ± 1.0 | | | ± 0.5 | | | * | | | % |
| $T_A = \text{min to max}$ | ± 2.5 | | | ± 1.5 | | | ± 1.0 | | | ± 2.0 | | | % |
| Total Error vs Temperature | ± 0.03 | | | ± 0.022 | | | ± 0.015 | | | ± 0.02 | | | %/°C |
| Scale Factor Error (SF = 10.000V Nominal) ⁽²⁾ | ± 0.25 | | | ± 0.1 | | | * | | | * | | | % |
| Temperature Coefficient of Scaling Voltage | ± 0.02 | | | ± 0.01 | | | ± 0.01 | | | * | | | %/°C |
| Supply Rejection ($\pm 15V \pm 1V$) | ± 0.01 | | | ± 0.01 | | | * | | | * | | | % |
| Nonlinearity | | | | | | | | | | | | | |
| X ($X = 20V_{p-p}, Y = 10V$) | ± 0.4 | | | ± 0.4 | | | 0.2 | | | * | | | % |
| Y ($Y = 20V_{p-p}, X = 10V$) | ± 0.01 | | | ± 0.01 | | | * | | | * | | | % |
| Feedthrough ⁽³⁾ | | | | | | | | | | | | | |
| X (Y Nulled, $X = 20V_{p-p}, 50\text{Hz}$) | ± 0.3 | | | ± 0.3 | | | ± 0.15 | | | * | | | % |
| Y (X Nulled, $Y = 20V_{p-p}, 50\text{Hz}$) | ± 0.01 | | | ± 0.01 | | | * | | | * | | | % |
| Both Inputs (500kHz, 1Vrms) | | | | | | | | | | | | | |
| Unnulled | 40 | 50 | | 45 | 55 | | * | 60 | | * | * | | dB |
| Nulled | 55 | 60 | | 55 | 65 | | 60 | 70 | | * | * | | dB |
| Output Offset Voltage | ± 50 | | | ± 5 | | | * | | | * | | | mV |
| Output Offset Voltage Drift | * | | | ± 200 | | | ± 100 | | | * | | | $\mu\text{V}/^\circ\text{C}$ |
| DYNAMICS | | | | | | | | | | | | | |
| Small Signal BW, ($V_{OUT} = 0.1V_{rms}$) | 6 | 10 | | 8 | 10 | | * | * | | 6 | * | | MHz |
| 1% Amplitude Error ($C_{LOAD} = 1000\text{pF}$) | 100 | | | 100 | | | * | | | * | | | kHz |
| Slew Rate ($V_{OUT} = 20V_{p-p}$) | 20 | | | 20 | | | * | | | * | | | V/ μs |
| Settling Time (to 1%, $\Delta V_{OUT} = 20V$) | 2 | | | 2 | | | * | | | * | | | μs |
| NOISE | | | | | | | | | | | | | |
| Noise Spectral Density: SF = 10V | 0.8 | | | 0.8 | | | * | | | * | | | $\mu\text{V}/\sqrt{\text{Hz}}$ |
| Wideband Noise: f = 10Hz to 5MHz | 1 | | | 1 | | | * | | | * | | | mVrms |
| f = 10Hz to 10kHz | 90 | | | 90 | | | * | | | * | | | μVrms |
| OUTPUT | | | | | | | | | | | | | |
| Output Voltage Swing | ± 11 | | | ± 11 | | | * | | | * | | | V |
| Output Impedance (f $\leq 1\text{kHz}$) | 0.1 | | | 0.1 | | | * | | | * | | | Ω |
| Output Short Circuit Current ($R_L = 0, T_A = \text{min to max}$) | 30 | | | 30 | | | * | | | * | | | mA |
| Amplifier Open Loop Gain (f = 50Hz) | 85 | | | 85 | | | * | | | * | | | dB |
| INPUT AMPLIFIERS (X, Y and Z) | | | | | | | | | | | | | |
| Input Voltage Range | | | | | | | | | | | | | |
| Differential V_{IN} ($V_{CM} = 0$) | ± 12 | | | ± 12 | | | * | | | * | | | V |
| Common-Mode V_{IN} ($V_{DIFF} = 0$) (see Typical Performance Curves) | ± 10 | | | ± 10 | | | * | | | * | | | V |
| Offset Voltage X, Y | ± 25 | | | ± 5 | | | ± 2 | | | * | | | mV |
| Offset Voltage Drift X, Y | 200 | | | 100 | | | 50 | | | * | | | $\mu\text{V}/^\circ\text{C}$ |
| Offset Voltage Z | ± 25 | | | ± 5 | | | ± 2 | | | * | | | mV |
| Offset Voltage Drift Z | 200 | | | 200 | | | 100 | | | 500 | | | $\mu\text{V}/^\circ\text{C}$ |
| CMRR | 60 | 80 | | 60 | 80 | | 70 | 90 | | * | * | | dB |
| Bias Current | 0.8 | | | 0.8 | | | 2.0 | | | * | | | μA |
| Offset Current | 0.1 | | | 0.1 | | | 2.0 | | | * | | | μA |
| Differential Resistance | 10 | | | 10 | | | * | | | * | | | M Ω |
| DIVIDER PERFORMANCE | | | | | | | | | | | | | |
| Transfer Function ($X_1 > X_2$) | $10V \frac{(Z_2 - Z_1)}{(X_1 - X_2)} + Y_1$ | | | $10V \frac{(Z_2 - Z_1)}{(X_1 - X_2)} + Y_1$ | | | * | | | * | | | |
| Total Error ⁽¹⁾ untrimmed ($X = 10V, -10V \leq Z \leq +10V$) | 1.5 | | | ± 0.75 | | | ± 0.35 | | | ± 0.75 | | | % |
| ($X = 1V, -1V \leq Z \leq +1V$) | 4.0 | | | ± 2.0 | | | ± 1.0 | | | * | | | % |
| ($0.1V \leq X \leq 10V, -10V \leq Z \leq 10V$) | 5.0 | | | ± 2.5 | | | ± 1.0 | | | * | | | % |
| SQUARE PERFORMANCE | | | | | | | | | | | | | |
| Transfer Function | $\frac{(X_1 - X_2)^2}{10V} + Z_2$ | | | $\frac{(X_1 - X_2)^2}{10V} + Z_2$ | | | * | | | * | | | |
| Total Error ($-10V \leq X \leq 10V$) | ± 1.2 | | | ± 0.6 | | | ± 0.3 | | | * | | | % |

SPECIFICATIONS (CONT)

ELECTRICAL

At $T_A = +25^\circ\text{C}$ and $V_S = \pm 15\text{VDC}$, unless otherwise noted.

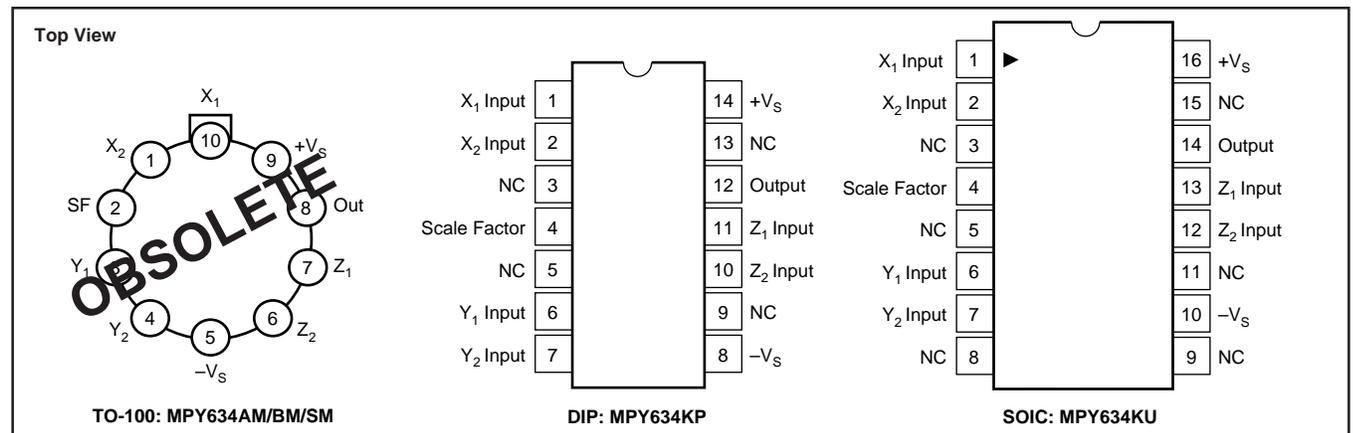
| MODEL | MPY634KP/KU | | | MPY634AM OBSOLETE | | | MPY634BM OBSOLETE | | | MPY634SM OBSOLETE | | | UNITS |
|---|--------------------------------------|----------|------------|--------------------------------------|----------|-------------|-----------------------------|-----|-----|-----------------------------|-----|-----------|--------------------------------------|
| | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | MIN | TYP | MAX | |
| SQUARE-ROOTER PERFORMANCE Transfer Function ($Z_1 \leq Z_2$) Total Error ⁽¹⁾ ($1\text{V} \leq Z \leq 10\text{V}$) | $\sqrt{10\text{V}(Z_2 - Z_1)} + X_2$ | | | $\sqrt{10\text{V}(Z_2 - Z_1)} + X_2$ | | | | * | | | * | | % |
| POWER SUPPLY Supply Voltage: Rated Performance Operating Supply Current, Quiescent | ± 8 | ± 15 | ± 18 | ± 8 | ± 15 | ± 18 | * | * | * | * | * | ± 20 | VDC VDC mA |
| TEMPERATURE RANGE Specification Storage | -40 -40 | | +85 +85 | -25 -65 | | +85 +150 | * | * | * | -55 * | | +125 * | $^\circ\text{C}$ $^\circ\text{C}$ |

* Specification same as for MPY634AM.

Gray indicates obsolete parts.

NOTES: (1) Figures given are percent of full scale, $\pm 10\text{V}$ (i.e., $0.01\% = 1\text{mV}$). (2) May be reduced to 3V using external resistor between $-V_S$ and SF. (3) Irreducible component due to nonlinearity; excludes effect of offsets.

PIN CONFIGURATIONS



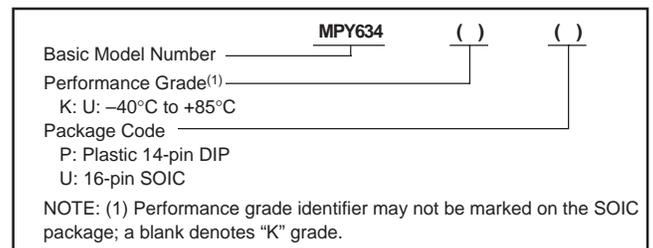
ABSOLUTE MAXIMUM RATINGS

| PARAMETER | MPY634AM/BM OBSOLETE | MPY634KP/KU | MPY634SM OBSOLETE |
|-----------------------------------|--|---------------------------------------|--|
| Power Supply Voltage | ± 18 | * | ± 20 |
| Power Dissipation | 500mW | * | * |
| Output Short-Circuit to Ground | Indefinite | * | * |
| Input Voltage (all X, Y and Z) | $\pm V_S$ | * | * |
| Temperature Range: | | | |
| Operating | $-25^\circ\text{C}/+85^\circ\text{C}$ | $-40^\circ\text{C}/+85^\circ\text{C}$ | $-55^\circ\text{C}/+125^\circ\text{C}$ |
| Storage | $-65^\circ\text{C}/+150^\circ\text{C}$ | $-40^\circ\text{C}/+85^\circ\text{C}$ | * |
| Lead Temperature (soldering, 10s) | +300 $^\circ\text{C}$ | * | * |
| SOIC 'KU' Package | | +260 $^\circ\text{C}$ | |

* Specification same as for MPY634AM/BM.

NOTE: Gray indicates obsolete parts.

ORDERING INFORMATION



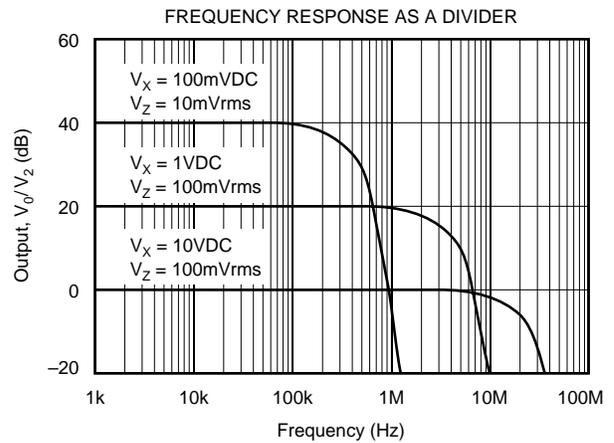
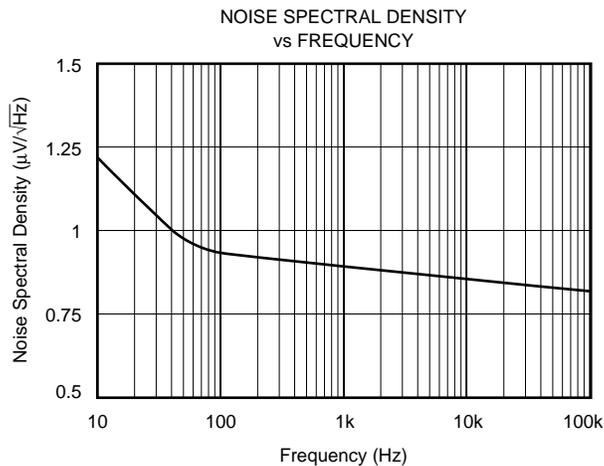
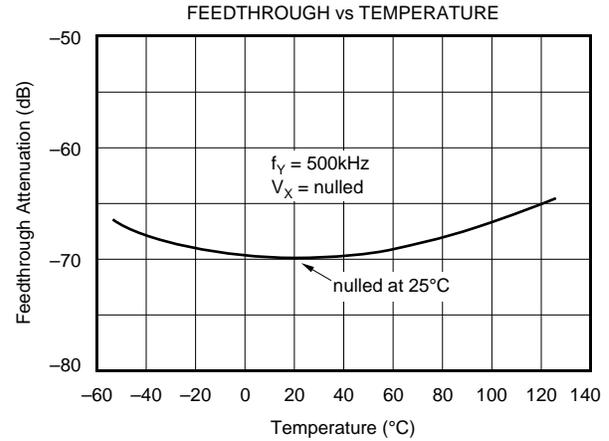
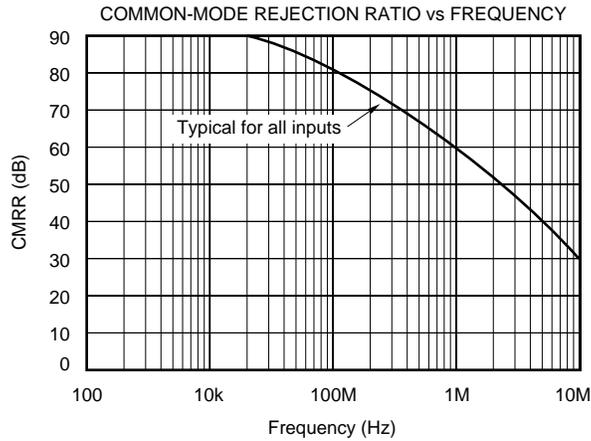
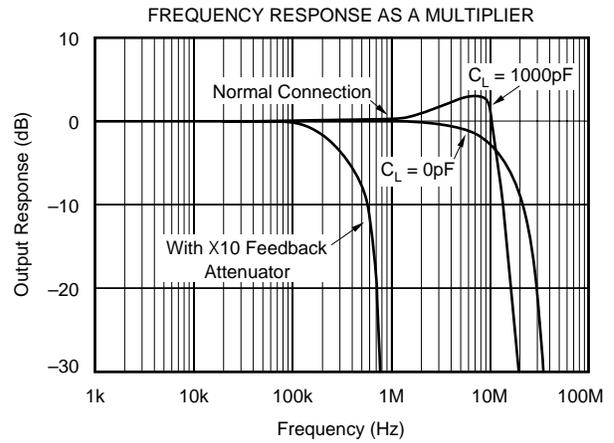
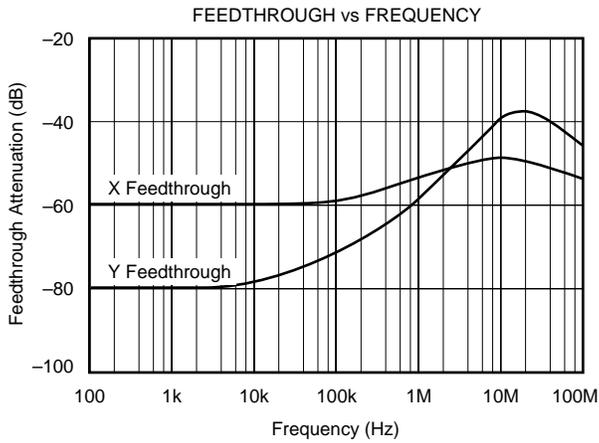
PACKAGE INFORMATION⁽¹⁾

| PRODUCT | PACKAGE | PACKAGE DRAWING NUMBER |
|----------|-------------|------------------------|
| MPY634KP | 14-Pin PDIP | 010 |
| MPY634KU | 16-Pin SOIC | 211 |

NOTE: (1) For the most current package and ordering information, see the Package Option Addendum located at the end of this data sheet.

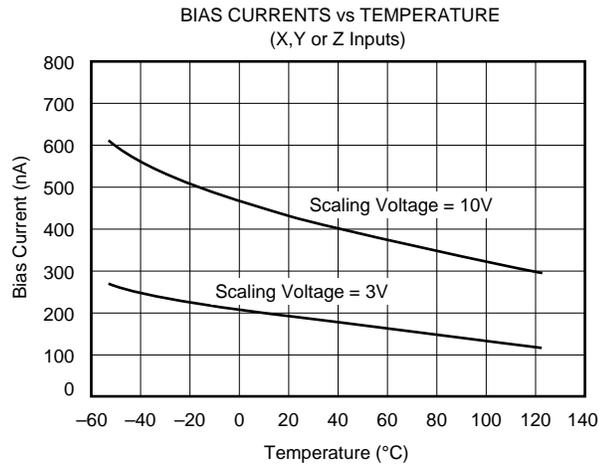
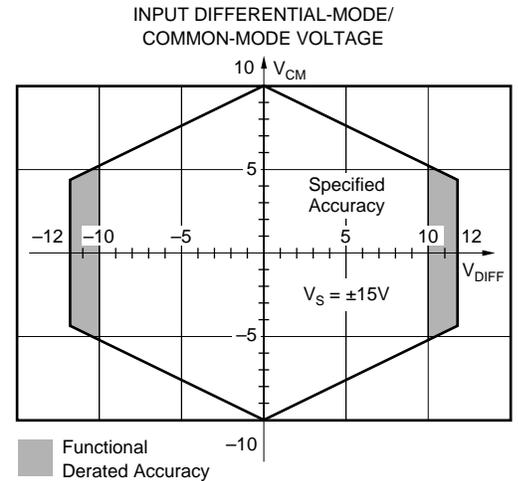
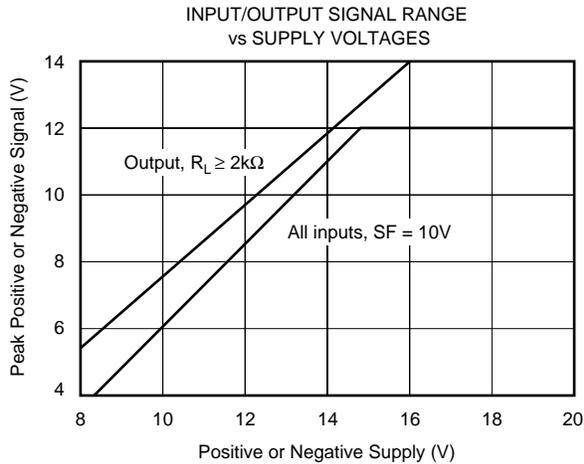
TYPICAL PERFORMANCE CURVES

At $T_A = +25^\circ\text{C}$, $V_S = \pm 15\text{VDC}$, unless otherwise noted.



TYPICAL PERFORMANCE CURVES (CONT)

$T_A = +25^\circ\text{C}$, $V_S = \pm 15\text{VDC}$, unless otherwise noted.



THEORY OF OPERATION

The transfer function for the MPY634 is:

$$V_{OUT} = A \left[\frac{(X_1 - X_2)(Y_1 - Y_2)}{SF} - (Z_1 - Z_2) \right]$$

where:

A = open-loop gain of the output amplifier (typically 85dB at DC).

SF = Scale Factor. Laser-trimmed to 10V but adjustable over a 3V to 10V range using external resistors.

X, Y, Z are input voltages. Full-scale input voltage is equal to the selected SF. (Max input voltage = ± 1.25 SF).

An intuitive understanding of transfer function can be gained by analogy to the op amp. By assuming that the open-loop gain, A, of the output operational amplifier is infinite,

inspection of the transfer function reveals that any V_{OUT} can be created with an infinitesimally small quantity within the brackets. Then, an application circuit can be analyzed by assigning circuit voltages for all X, Y and Z inputs and setting the bracketed quantity equal to zero. For example, the basic multiplier connection in Figure 1, $Z_1 = V_{OUT}$ and $Z_2 = 0$. The quantity within the brackets then reduces to:

$$\frac{(X_1 - X_2)(Y_1 - Y_2)}{SF} - (V_{OUT} - 0) = 0$$

This approach leads to a simple relationship which can be solved for V_{OUT} to provide the closed-loop transfer function.

The scale factor is accurately factory adjusted to 10V and is typically accurate to within 0.1% or less. The scale factor may be adjusted by connecting a resistor or potentiometer between pin SF and the $-V_S$ power supply. The value of the external resistor can be approximated by:

$$R_{SF} = 5.4k\Omega \left(\frac{SF}{10 - SF} \right)$$

Internal device tolerances make this relationship accurate to within approximately 25%. Some applications can benefit from reduction of the SF by this technique. The reduced input bias current, noise, and drift achieved by this technique can be likened to operating the input circuitry in a higher gain, thus reducing output contributions to these effects. Adjustment of the scale factor does not affect bandwidth.

The MPY634 is fully characterized at $V_S = \pm 15V$ but operation is possible down to $\pm 8V$ with an attendant reduction of input and output range capability. Operation at voltages greater than $\pm 15V$ allows greater output swing to be achieved by using an output feedback attenuator (Figure 1).

As with any wide bandwidth circuit, the power supplies should be bypassed with high frequency ceramic capacitors. These capacitors should be located as near as practical to the power supply connections of the MPY634. Improper bypassing can lead to instability, overshoot, and ringing in the output.

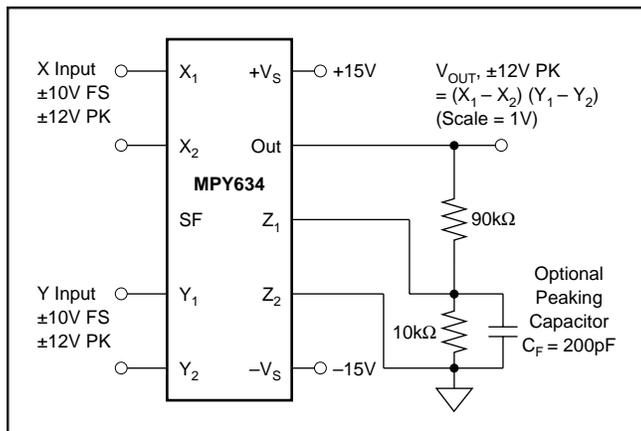


FIGURE 1. Connections for Scale-Factor of Unity.

BASIC MULTIPLIER CONNECTION

Figure 2 shows the basic connection as a multiplier. Accuracy is fully specified without any additional user-trimming circuitry. Some applications can benefit from trimming of one or more of the inputs. The fully differential inputs facilitate referencing the input quantities to the source voltage common terminal for maximum accuracy. They also allow use of simple offset voltage trimming circuitry as shown on the X input.

The differential Z input allows an offset to be summed in V_{OUT} . In basic multiplier operation, the Z_2 input serves as the output voltage ground reference and should be connected to the ground of the driven system for maximum accuracy.

A method of changing (lowering) SF by connecting to the SF pin was discussed previously. Figure 1 shows an alternative method of changing the effective SF of the overall circuit by using an attenuator in the feedback connection to Z_1 . This method puts the output amplifier in a higher gain and is thus accompanied by a reduction in bandwidth and an

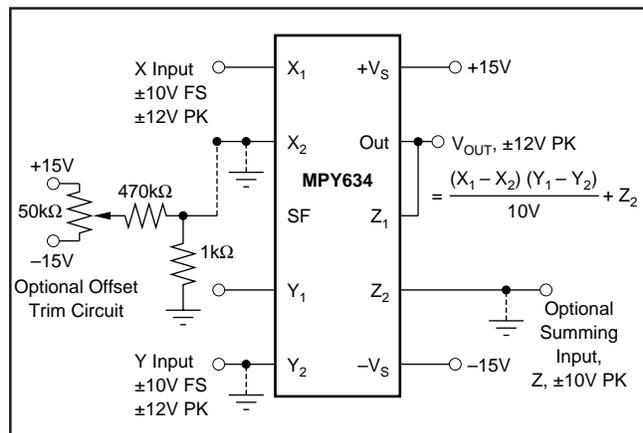


FIGURE 2. Basic Multiplier Connection.

increase in output offset voltage. The larger output offset may be reduced by applying a trimming voltage to the high impedance input, Z_2 .

The flexibility of the differential Z inputs allows direct conversion of the output quantity to a current. Figure 3 shows the output voltage differentially-sensed across a series resistor forcing an output-controlled current. Addition of a capacitor load then creates a time integration function useful in a variety of applications such as power computation.

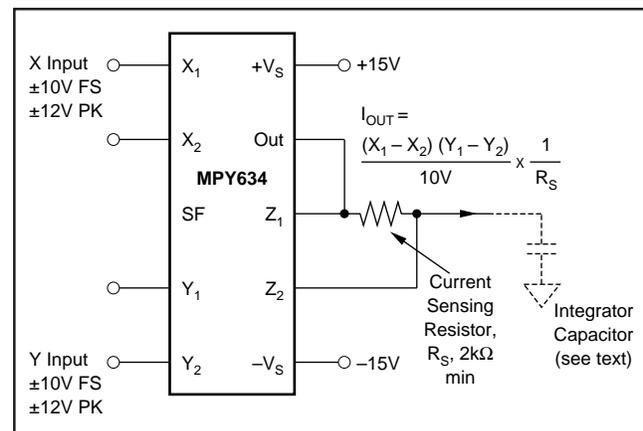


FIGURE 3. Conversion of Output to Current.

SQUARER CIRCUIT (FREQUENCY DOUBLER)

Squarer, or frequency doubler, operation is achieved by paralleling the X and Y inputs of the standard multiplier circuit. Inverted output can be achieved by reversing the differential input terminals of either the X or Y input. Accuracy in the squaring mode is typically a factor of two better than the specified multiplier mode with maximum error occurring with small (less than 1V) inputs. Better accuracy can be achieved for small input voltage levels by reducing the scale factor, SF.

DIVIDER OPERATION

The MPY634 can be configured as a divider as shown in Figure 4. High impedance differential inputs for the numerator and denominator are achieved at the Z and X inputs,

respectively. Feedback is applied to the Y_2 input, and Y_1 is normally referenced to output ground. Alternatively, as the transfer function implies, an input applied to Y_1 can be summed directly into V_{OUT} . Since the feedback connection is made to a multiplying input, the effective gain of the output op amp varies as a function of the denominator input voltage. Therefore, the bandwidth of the divider function is proportional to the denominator voltage (see Typical Performance Curves).

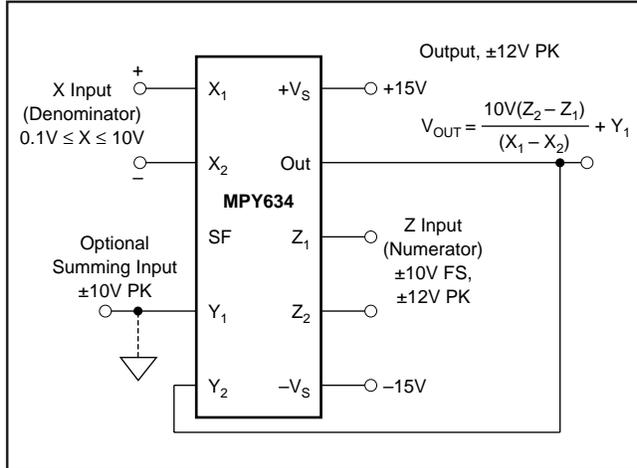


FIGURE 4. Basic Divider Connection.

Accuracy of the divider mode typically ranges from 1.0% to 2.5% for a 10 to 1 denominator range depending on device grade. Accuracy is primarily limited by input offset voltages and can be significantly improved by trimming the offset of the X input. A trim voltage of $\pm 3.5\text{mV}$ applied to the “low side” X input (X_2 for positive input voltages on X_1) can produce similar accuracies over 100 to 1 denominator range. To trim, apply a signal which varies from 100mV to 10V at a low frequency (less than 500Hz). An offset sine wave or ramp is suitable. Since the ratio of the quantities should be constant, the ideal output would be a constant 10V. Using AC coupling on an oscilloscope, adjust the offset control for minimum output voltage variation.

SQUARE-ROOTER

A square-rooter connection is shown in Figure 5. Input voltage is limited to one polarity (positive for the connection shown). The diode prevents circuit latch-up should the input go negative. The circuit can be configured for negative input and positive output by reversing the polarity of both the X and Y inputs. The output polarity can be reversed by reversing the diode and X input polarity. A load resistance of approximately 10k Ω must be provided. Trimming for improved accuracy would be accomplished at the Z input.

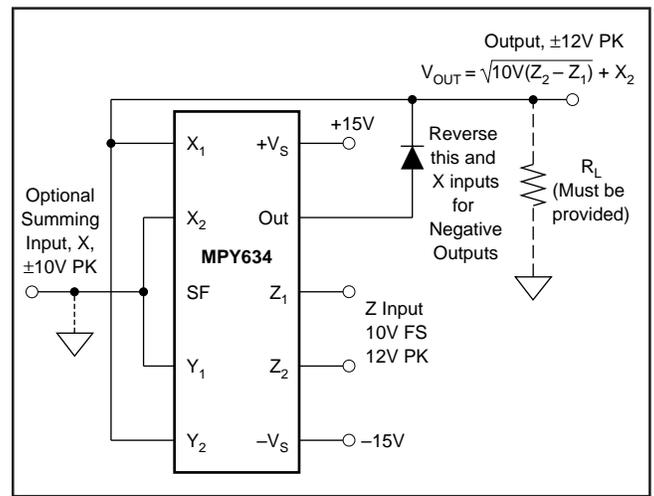


FIGURE 5. Square-Rooter Connection.

APPLICATIONS

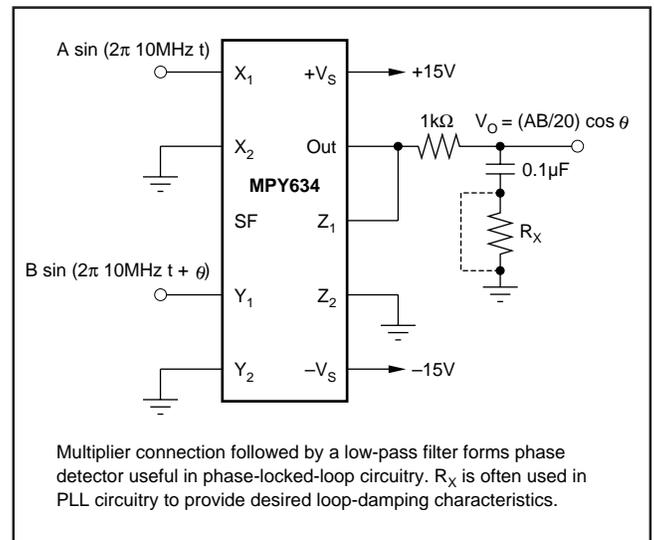


FIGURE 6. Phase Detector.

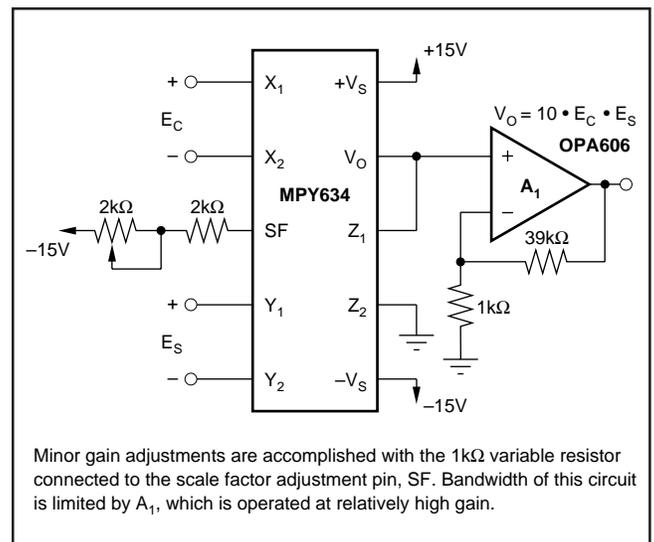


FIGURE 7. Voltage-Controlled Amplifier.

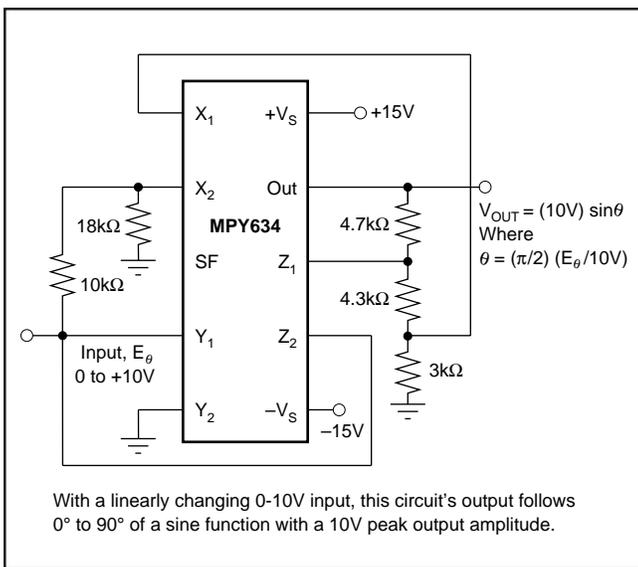


FIGURE 8. Sine-Function Generator.

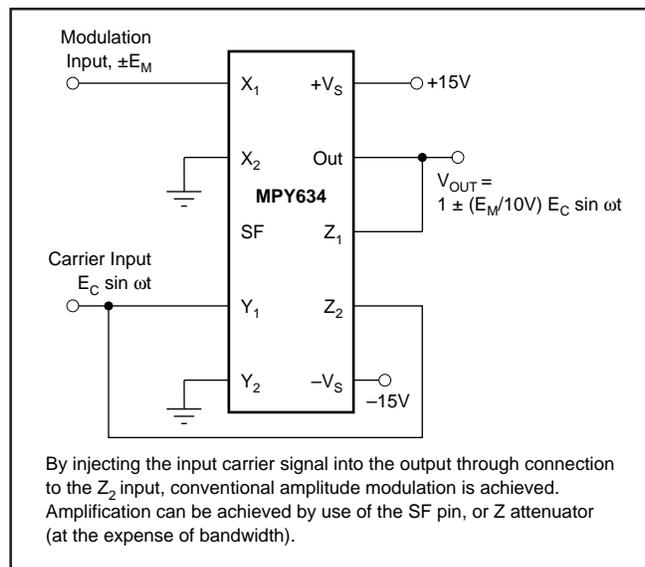


FIGURE 9. Linear AM Modulator.

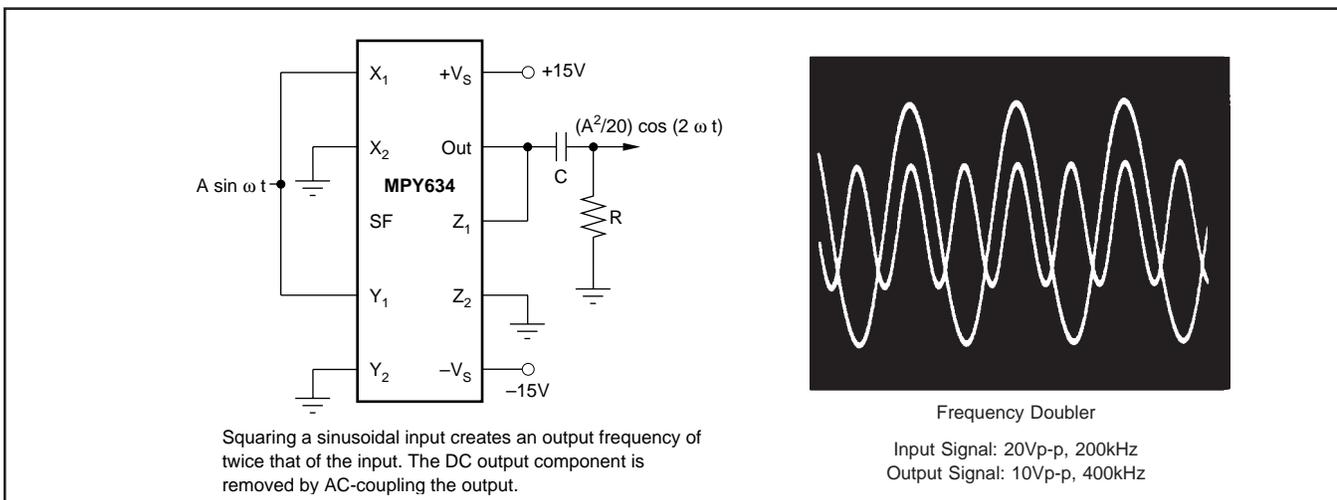


FIGURE 10. Frequency Doubler.

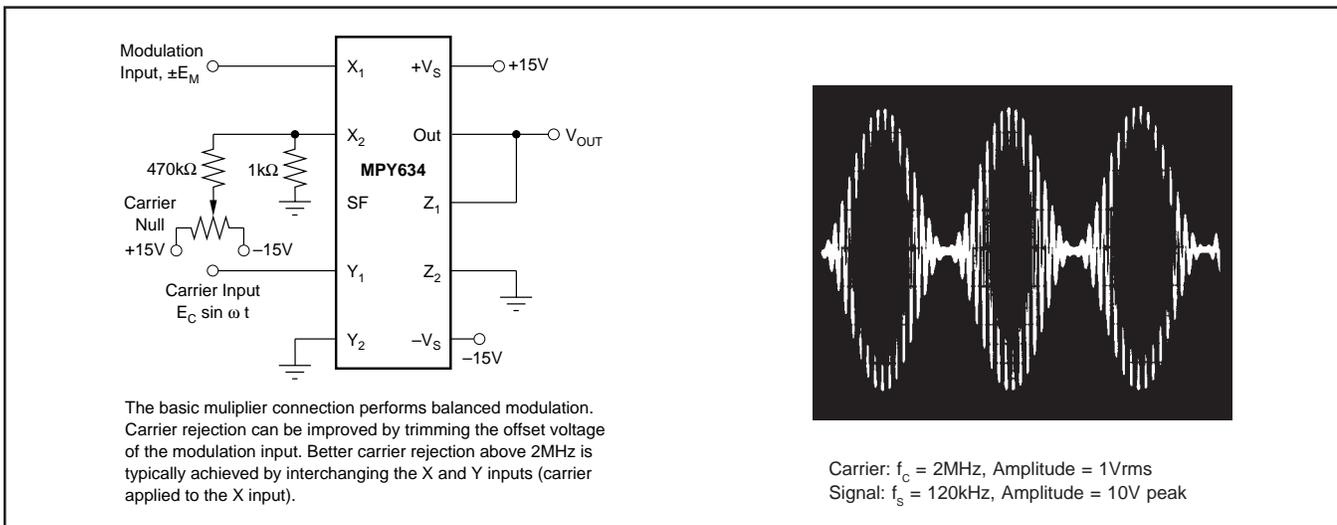


FIGURE 11. Balanced Modulator.

PACKAGING INFORMATION

| Orderable Device | Status ⁽¹⁾ | Package Type | Package Drawing | Pins | Package Qty | Eco Plan ⁽²⁾ | Lead/Ball Finish | MSL Peak Temp ⁽³⁾ |
|------------------|-----------------------|--------------|-----------------|------|-------------|-------------------------|------------------|------------------------------|
| MPY634AM | OBSOLETE | TO-100 | LME | 10 | | TBD | Call TI | Call TI |
| MPY634BM | OBSOLETE | TO-100 | LME | 10 | | TBD | Call TI | Call TI |
| MPY634KP | ACTIVE | PDIP | N | 14 | 25 | Green (RoHS & no Sb/Br) | CU NIPDAU | N / A for Pkg Type |
| MPY634KPG4 | ACTIVE | PDIP | N | 14 | 25 | Green (RoHS & no Sb/Br) | CU NIPDAU | N / A for Pkg Type |
| MPY634KU | ACTIVE | SOIC | DW | 16 | 40 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |
| MPY634KU/1K | ACTIVE | SOIC | DW | 16 | 1000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |
| MPY634KU/1KE4 | ACTIVE | SOIC | DW | 16 | 1000 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |
| MPY634KUE4 | ACTIVE | SOIC | DW | 16 | 40 | Green (RoHS & no Sb/Br) | CU NIPDAU | Level-3-260C-168 HR |

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

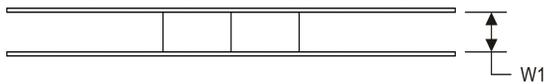
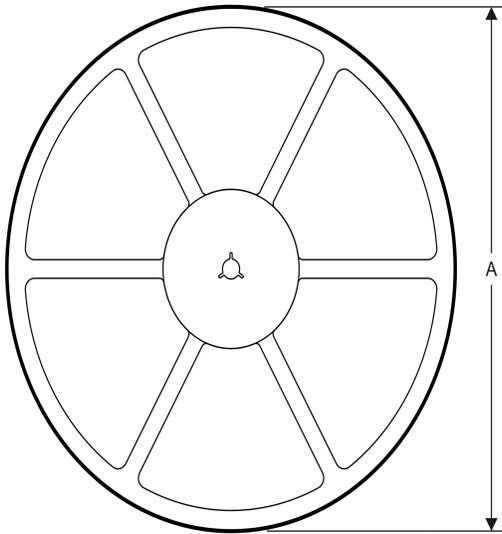
⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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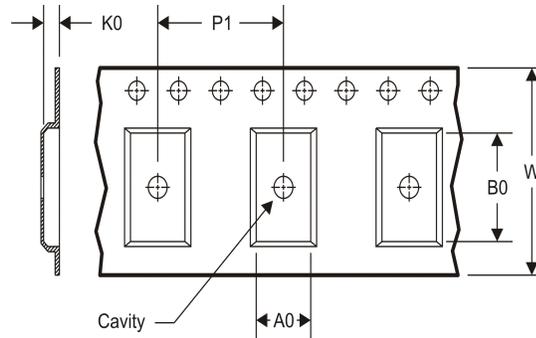
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TAPE AND REEL INFORMATION

REEL DIMENSIONS



TAPE DIMENSIONS



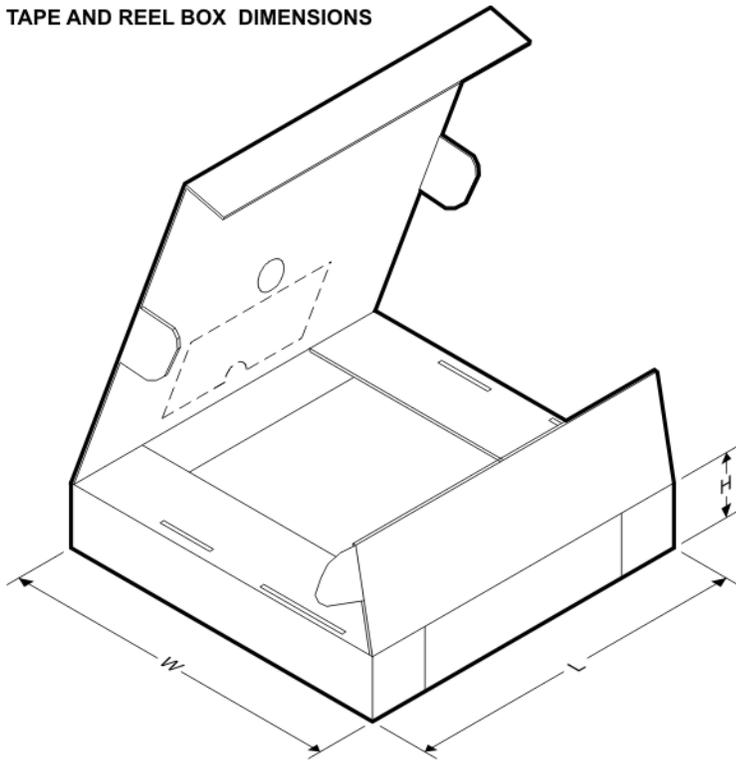
| | |
|----|---|
| A0 | Dimension designed to accommodate the component width |
| B0 | Dimension designed to accommodate the component length |
| K0 | Dimension designed to accommodate the component thickness |
| W | Overall width of the carrier tape |
| P1 | Pitch between successive cavity centers |

TAPE AND REEL INFORMATION

*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| MPY634KU/1K | SOIC | DW | 16 | 1000 | 330.0 | 16.4 | 10.75 | 10.7 | 2.7 | 12.0 | 16.0 | Q1 |

TAPE AND REEL BOX DIMENSIONS

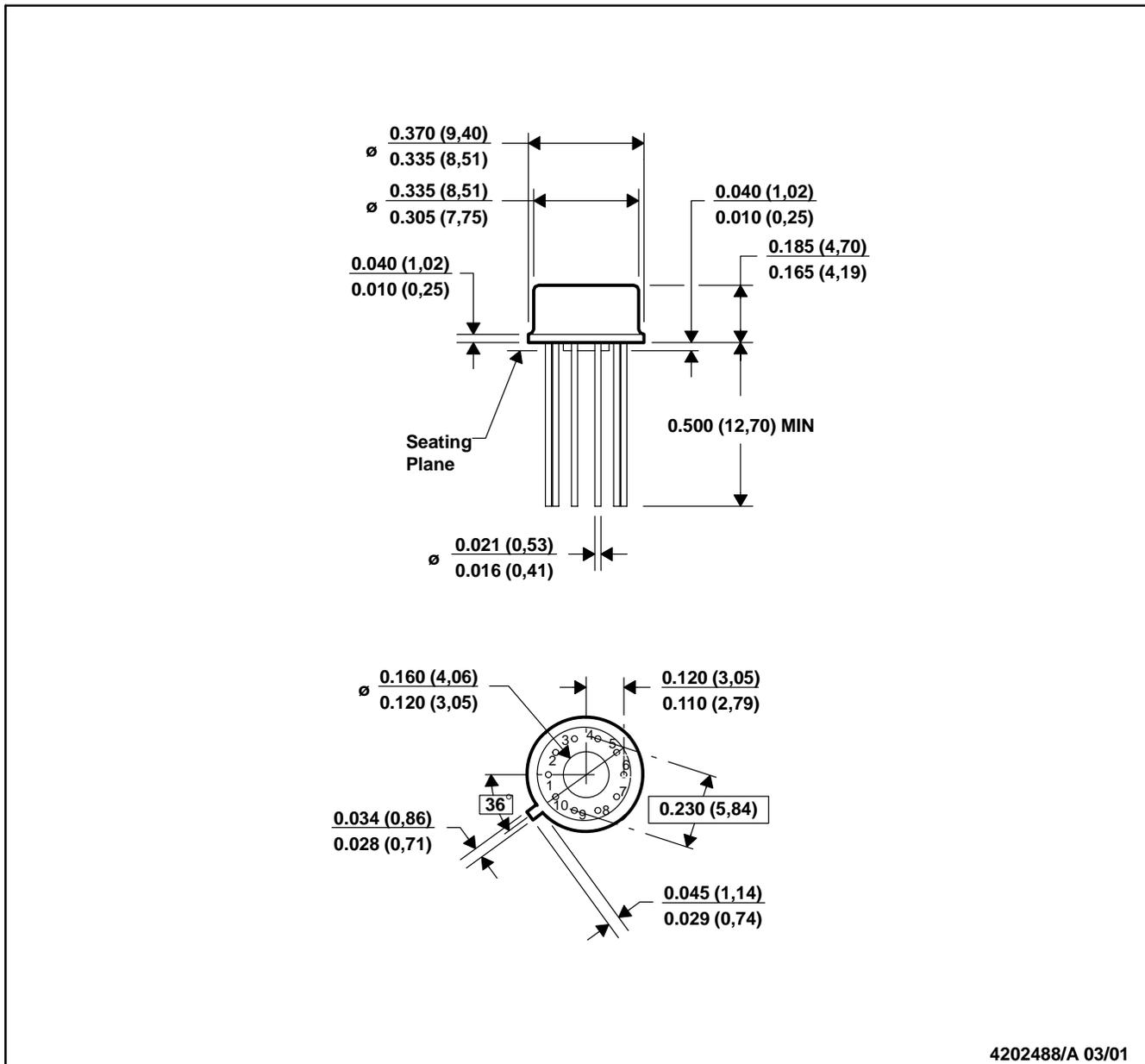


*All dimensions are nominal

| Device | Package Type | Package Drawing | Pins | SPQ | Length (mm) | Width (mm) | Height (mm) |
|-------------|--------------|-----------------|------|------|-------------|------------|-------------|
| MPY634KU/1K | SOIC | DW | 16 | 1000 | 367.0 | 367.0 | 38.0 |

LME (O-MBCY-W10)

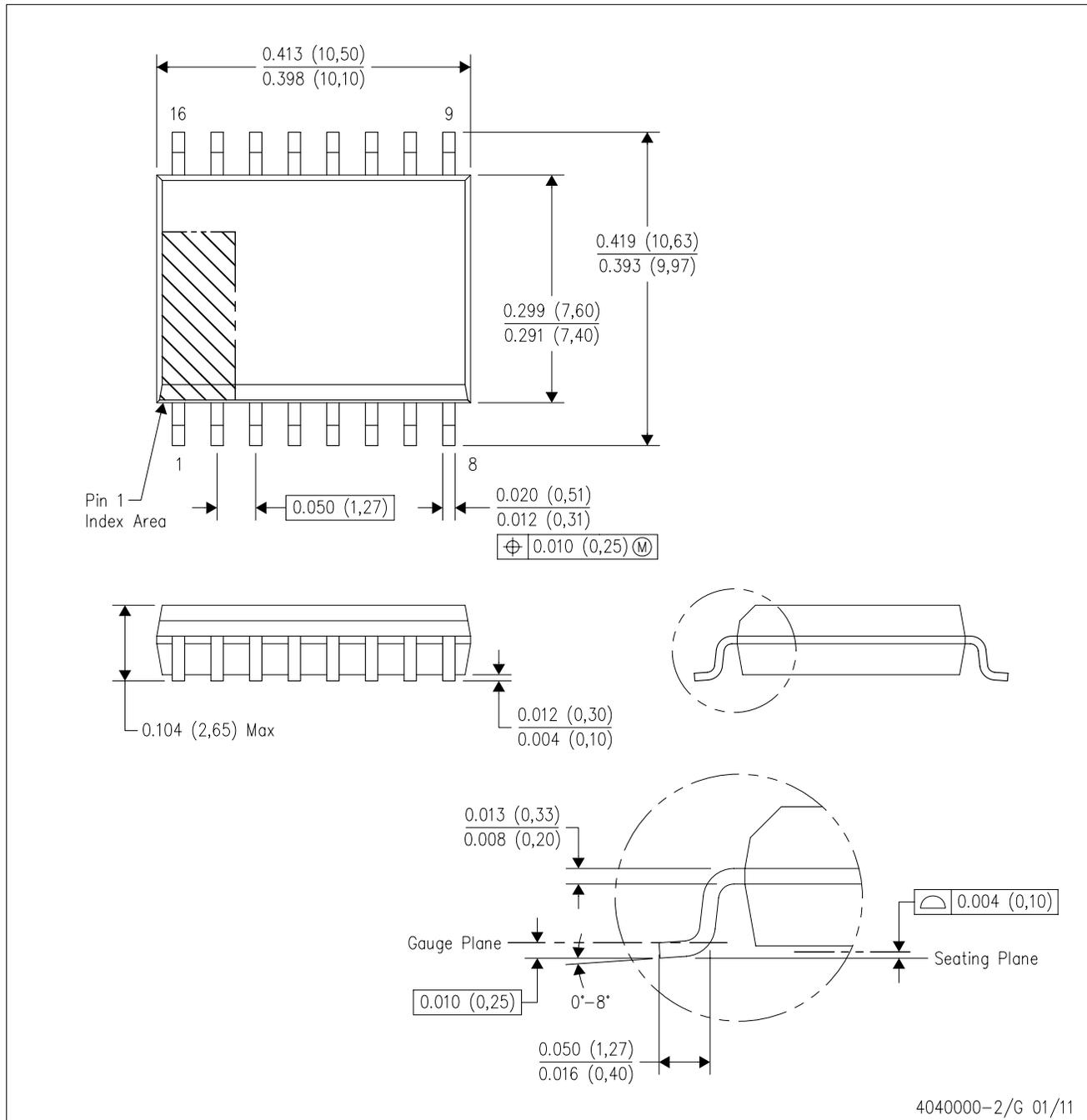
METAL CYLINDRICAL PACKAGE



- NOTES: A. All linear dimensions are in inches (millimeters).
 B. This drawing is subject to change without notice.
 C. Leads in true position within 0.010 (0,25) R @ MMC at seating plane.
 D. Pin numbers shown for reference only. Numbers may not be marked on package.
 E. Falls within JEDEC MO-006/TO-100.

DW (R-PDSO-G16)

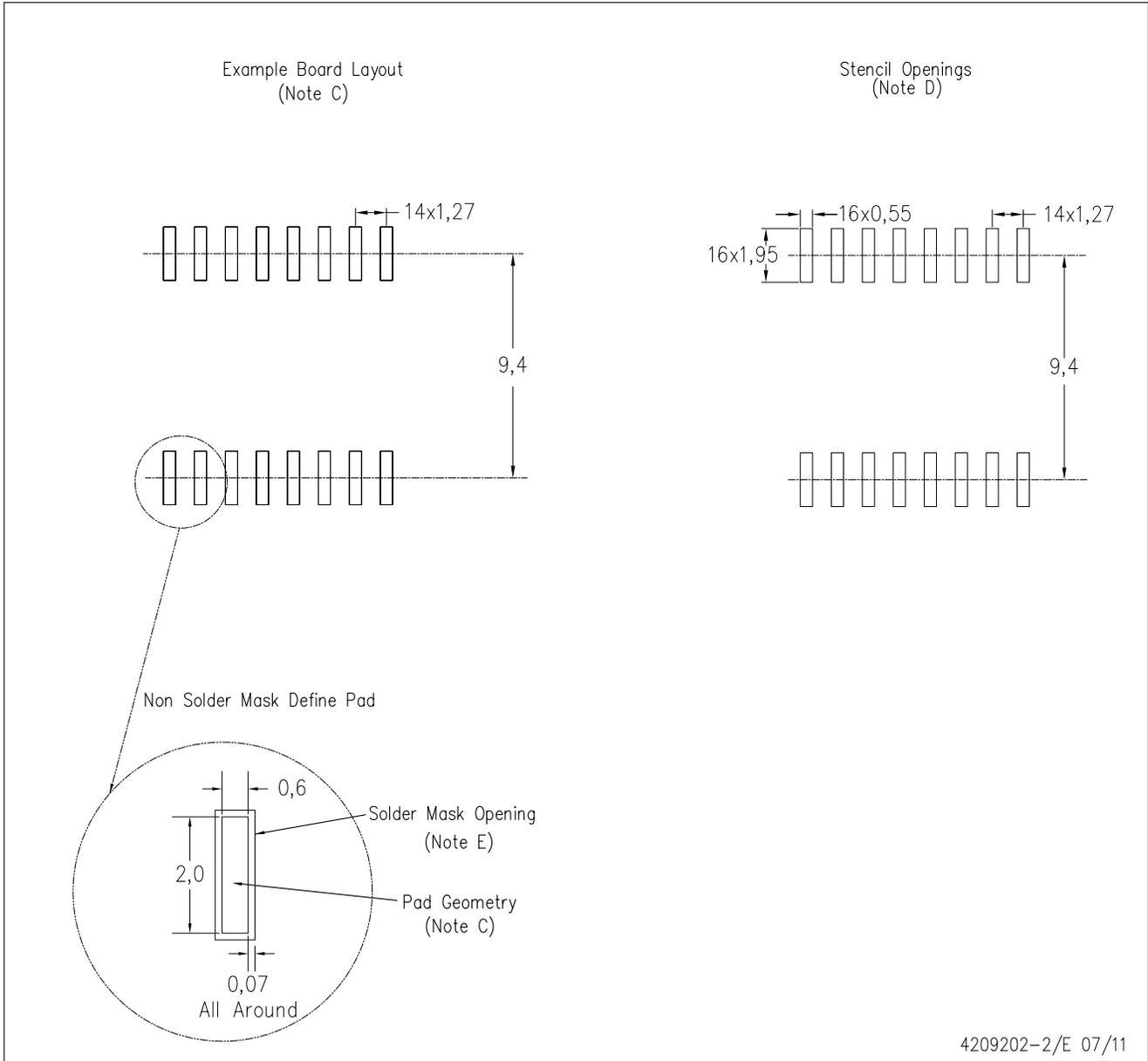
PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in inches (millimeters). Dimensioning and tolerancing per ASME Y14.5M-1994.
 - B. This drawing is subject to change without notice.
 - C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
 - D. Falls within JEDEC MS-013 variation AA.

DW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in millimeters.
 - B. This drawing is subject to change without notice.
 - C. Refer to IPC7351 for alternate board design.
 - D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525
 - E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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